Multi-technique comparison of troposphere zenith delays and gradients during CONTO8



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The aims of our study are

- · Quantify agreement of troposphere estimates
- · Figure out site and technique specific irregularities

Agreement criteria are

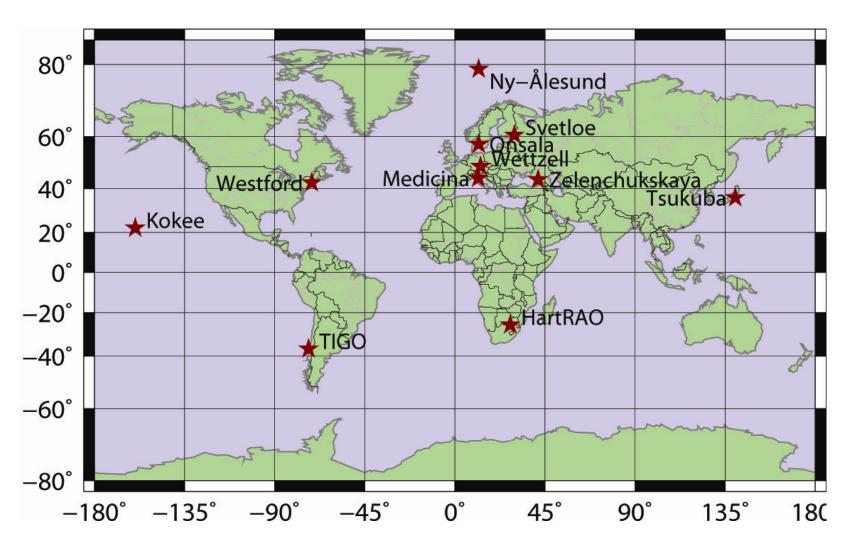
$$e.g. \quad x_{i} = ZTD_{i}^{VLBI-VieVS} \quad y_{i} = ZTD_{i}^{GPS-CODE} \quad \Delta_{i} = x_{i} - y_{i}$$

$$\overline{\Delta} = \frac{1}{n} \sum_{i=1}^{n} \Delta_{i} \qquad i = 1, 2, \dots, n$$

$$Sx = \left[\frac{1}{n-1} \sum_{i=1}^{n} (\Delta_{i} - \overline{\Delta})^{2}\right]^{\frac{1}{2}}$$

$$r_{xy} = \frac{Cov(x, y)}{S_{x} S_{y}} = \frac{\sum_{i=1}^{n} (x_{i} - \overline{x})(y_{i} - \overline{y})}{\left[\sum_{i=1}^{n} (x_{i} - \overline{x})^{2} \cdot \sum_{i=1}^{n} (y_{i} - \overline{y})^{2}\right]^{\frac{1}{2}}} \qquad (p < 0.05)$$

CONTO8 co-located sites



first observation: Tuesday August 12, 2008 @ 00:00:00 UT

last observation: Tuesday August 26, 2008 @ 23:59:59 UT

<u>Very Long Baseline Interferometry (VLBI)</u>

- Vienna VLBI Software (VieVS):
- NNT/NNR on ITRF2005.
- VMF1, above 5°.
- 0.7 picosec²/sec for ZTDs (relatively loose).
- 2 mm/day for gradients (relatively loose).
- 30 minutes for ZTDs, and 120 for gradients.
- APL applied a priori (Petrov and Boy, 2004)
- · <u>International VLBI Service for Geodesy and Astrometry</u> (IVS):
- -Intra-technique combined solution for ZTDs and troposphere gradients.
- -60 minutes for ZTDs and for gradients

Global Positioning System (GPS)

- · Center for Orbit Determination in Europe (CODE)
- Bernese GPS software.
- NNR on IGS05.
- 120 minutes interval for ZTDs and 24 h for gradients.
- VMF1, 3° + elevation dependent weighting.
- No constraints for zenith delays and gradients.
- APL applied.

International GNSS Service (IGS)

- GIPSY/Oasis software.
- PPP solution, Kalman filter.
- IGS final combined: orbits, clocks, and EOP.
- NMF, 7°.
- 5 minutes for ZTDs.
- Estimated parameters are: clocks, station position, zenith wet delay, troposphere gradients, phase biases (Byun S.H. and Bar-Sever Y.E., 2009).

<u>Doppler Orbitography and Radio Positioning</u> <u>Integrated by Satellite (DORIS)</u>

- · <u>Institut Géographique National (IGN)</u>
- Software is GIPSY/Oasis.
- TRF is fixed to ign09d02.
- VMF1, 10°.
- DORIS reset at no regular interval.
- It is reset at start of pass and only if the previous reset is 20 minutes before or earlier.
- ZTD epochs interpolated linearly from the irregular epochs to 120 minutes (epochs at UTC integer hours).
- No interpolation between the data gaps larger than 60 minutes.
- Co-located sites are Ny-Ålesund (spjb), Kokee Park (kolb), Hartebeesthoek (hbmb).

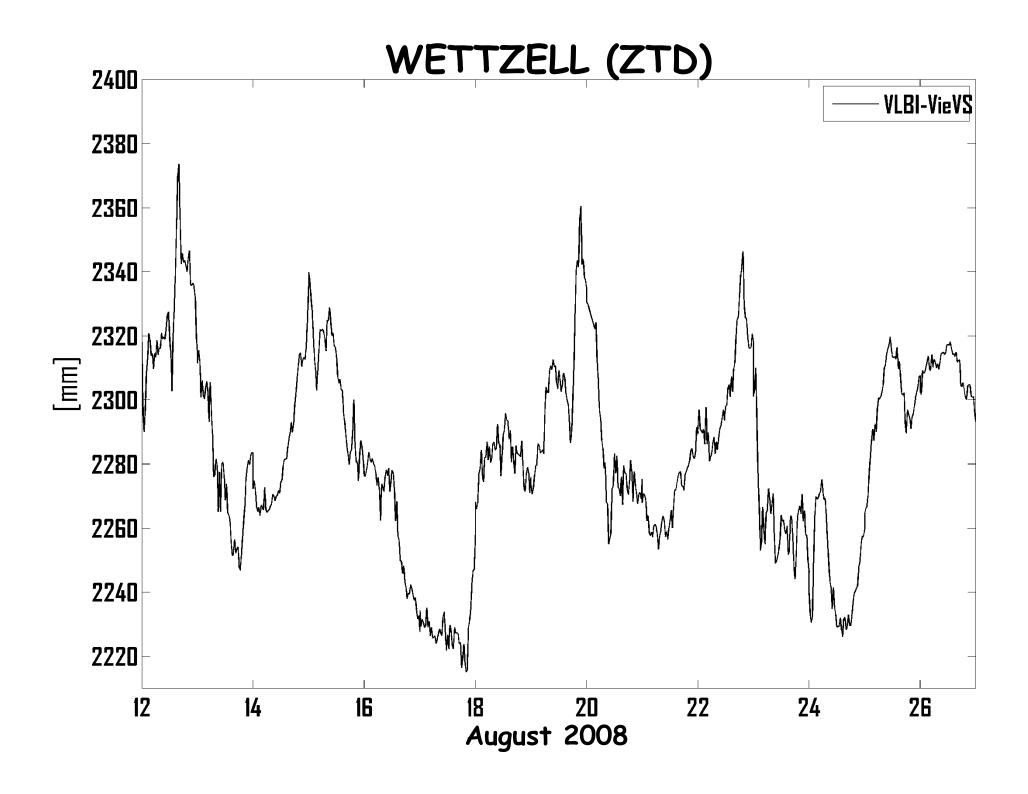
<u>Water Vapor Radiometer (WVR)</u>

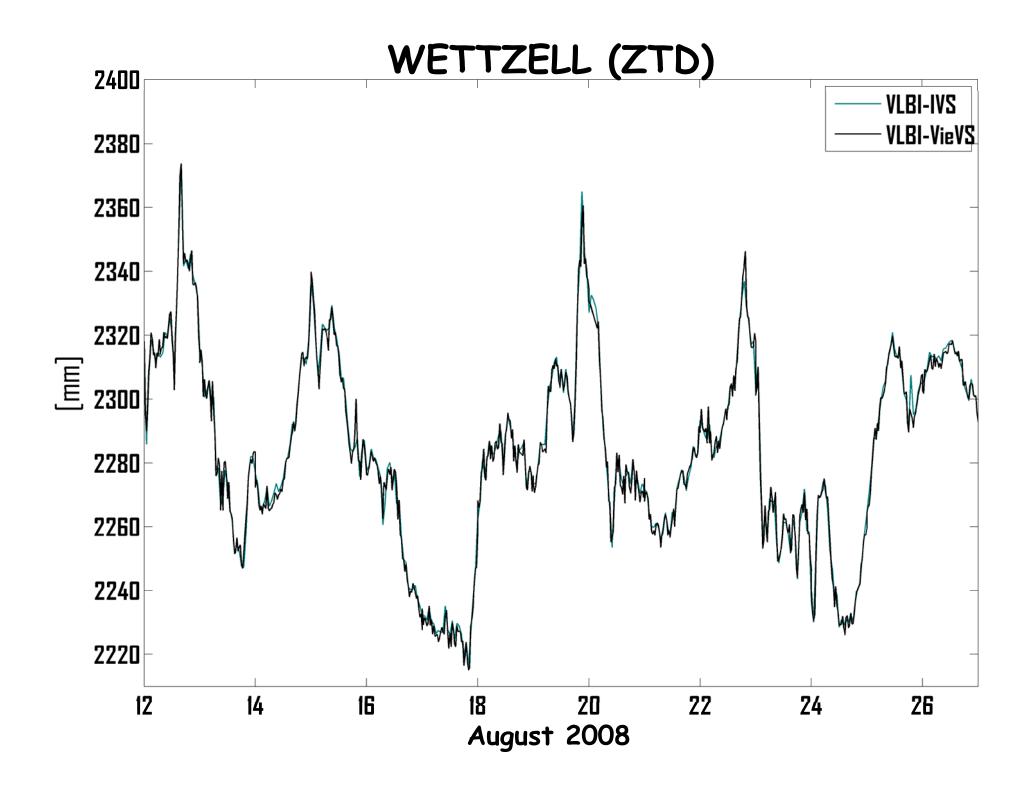
- Slant wet delays inferred from measurements of the sky brightness temperature at about 22 GHz and 31 GHz.
- ZWDs and gradients obtained by a least-squares fit. 30 minutes estimation interval for ZWDs and 120 minutes estimation intervals for troposphere gradients.
- ZHDs calculated from surface pressure measurements at the VLBI antenna.
- Cut off 20°.
- Data aquired during rain removed.
- Co-located sites: Wettzell, Tsukuba, and Onsala.

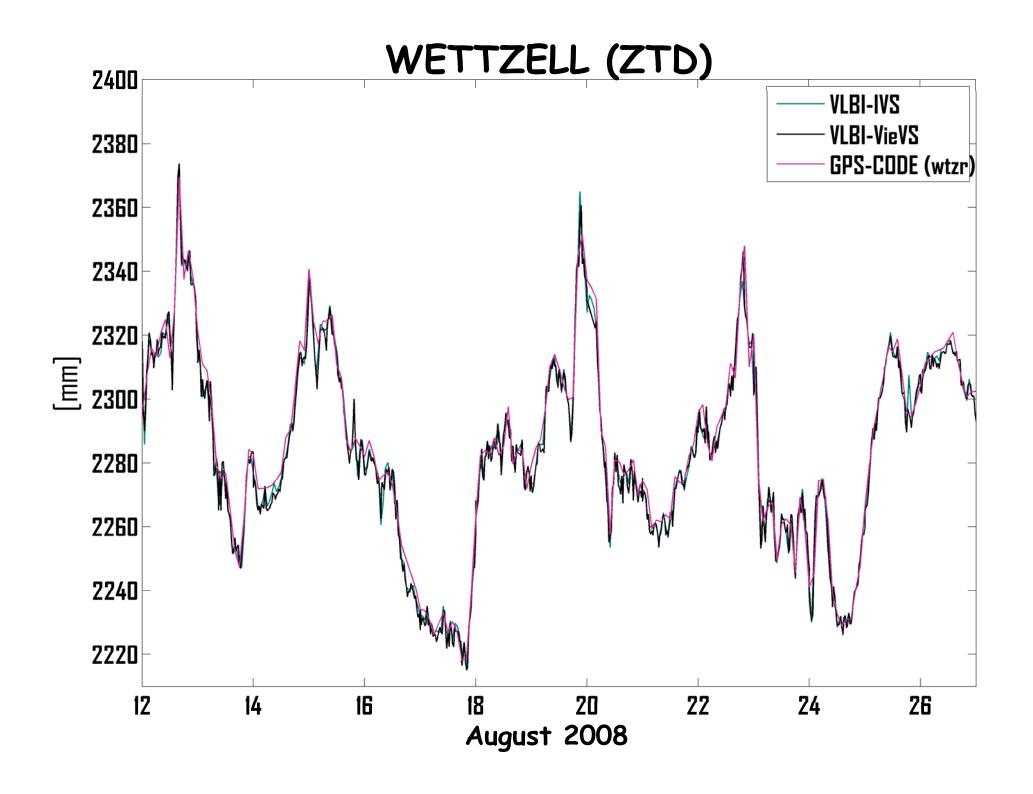
Numerical Weather Models (NWMs)

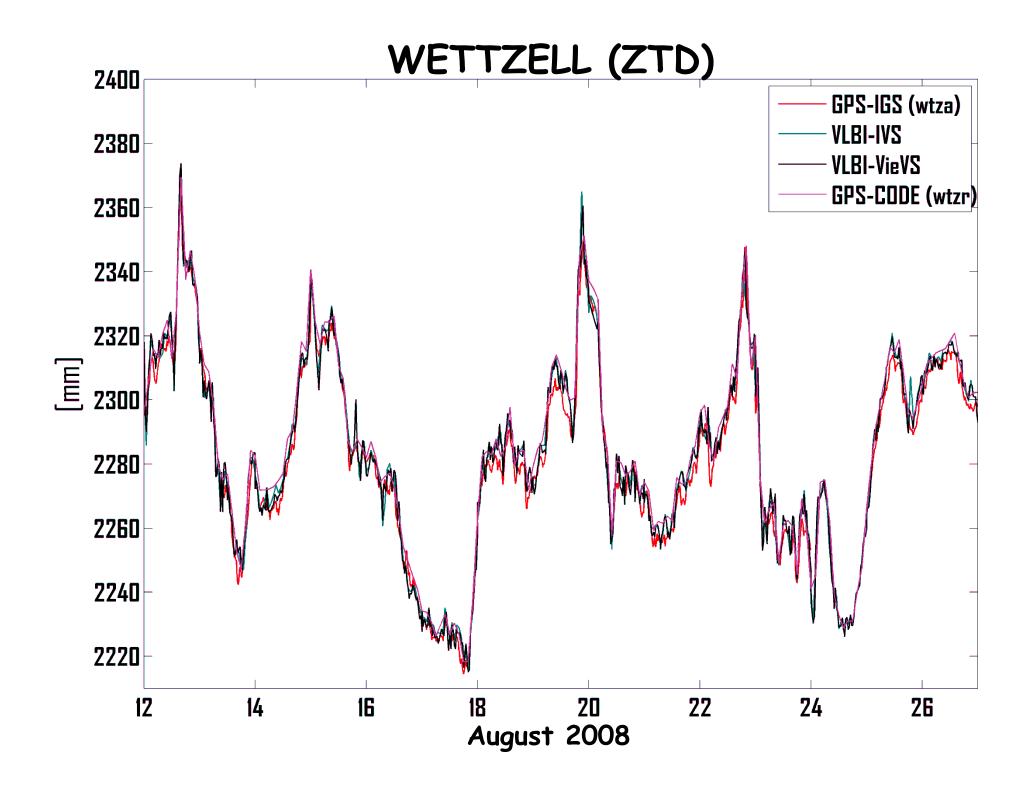
- ·Japan <u>Meteorological Agency</u> <u>Kashima Ray-Tracing Tools</u> (JMA-KARAT).
- · <u>High Resolution Limited Area Model (HIRLAM)</u>.
- <u>European Centre for Medium-Range Weather Forecasts</u> (<u>ECMWF</u>).

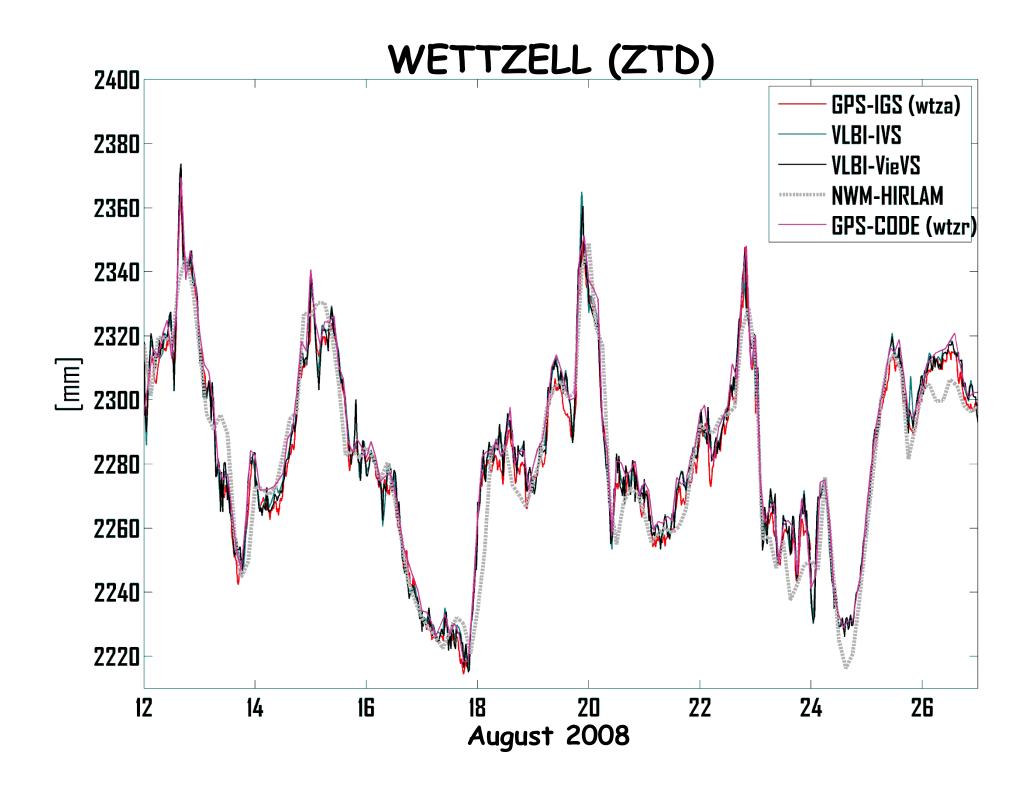
NWM	The regions for which the models provide data	Spatial resolution	Time Resolution (hours)	Number of levels at each profile	Troposphere gradients estimated?
JMA-KARAT	Japan	0.1°	3	21	YES
HIRLAM	Europe	0.2°	3	40	NO
ECMWF	Global	0.25°	6	21	YES

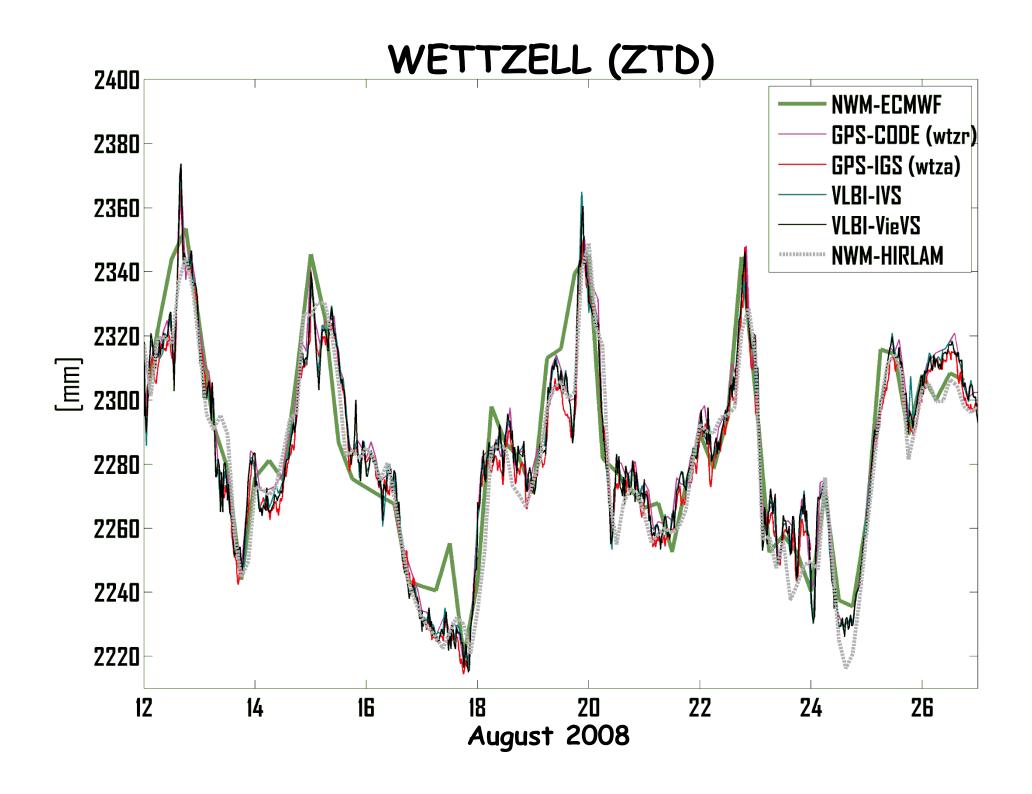


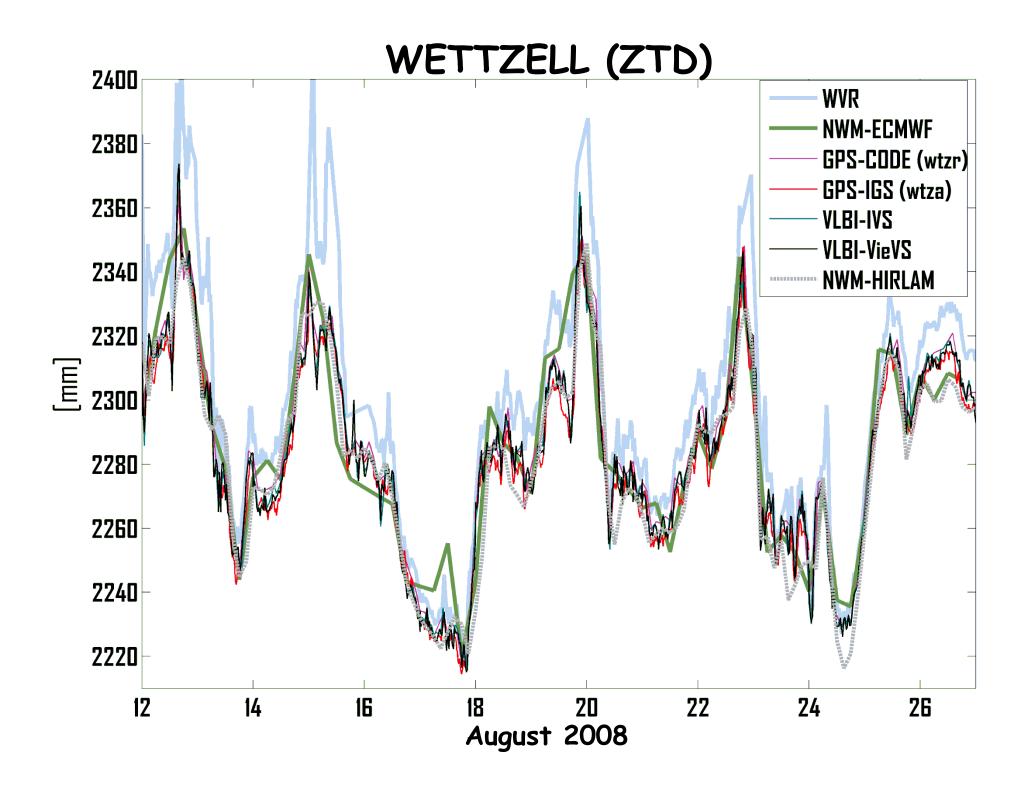


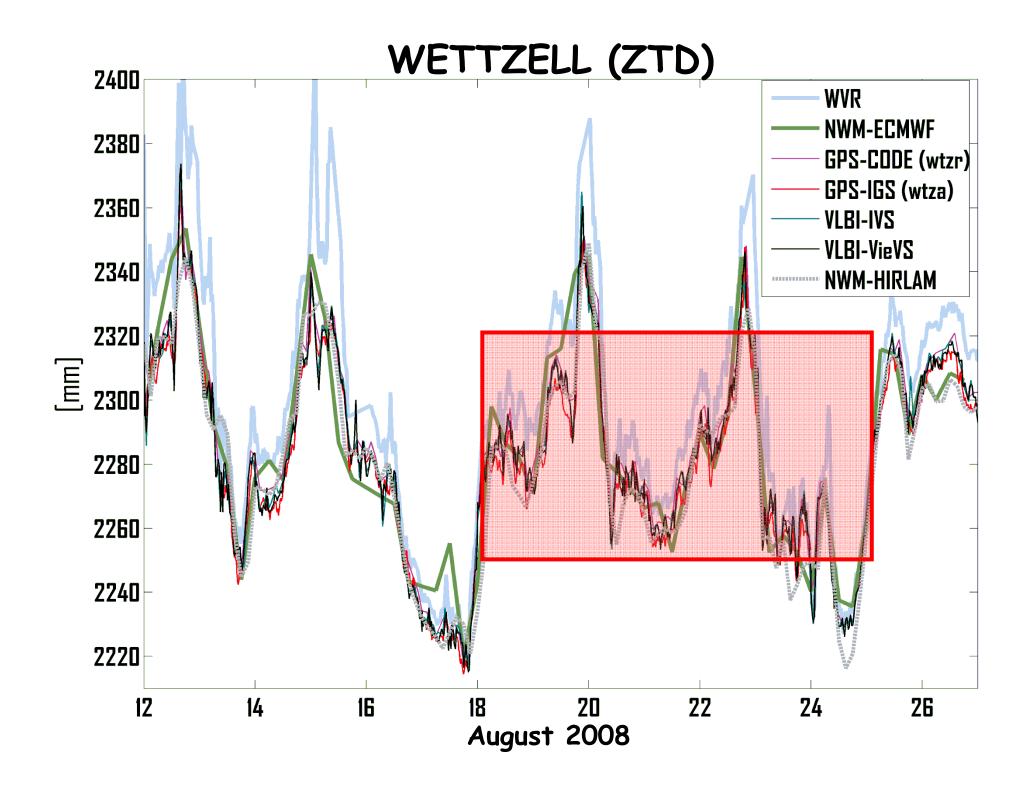


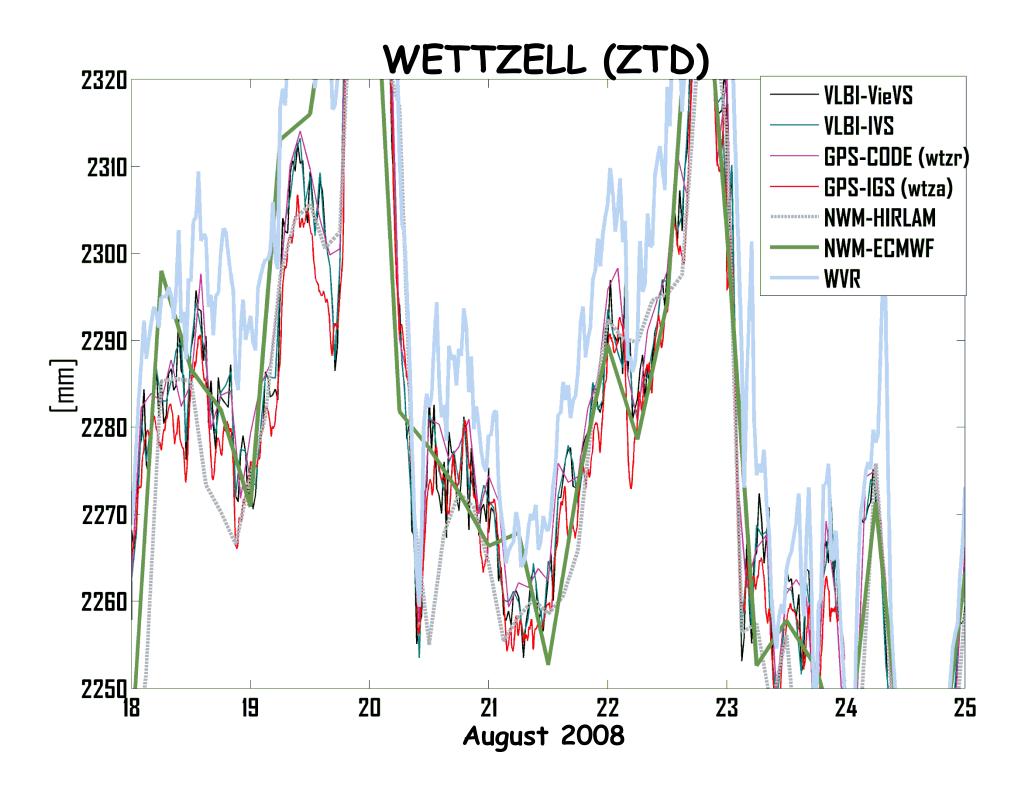




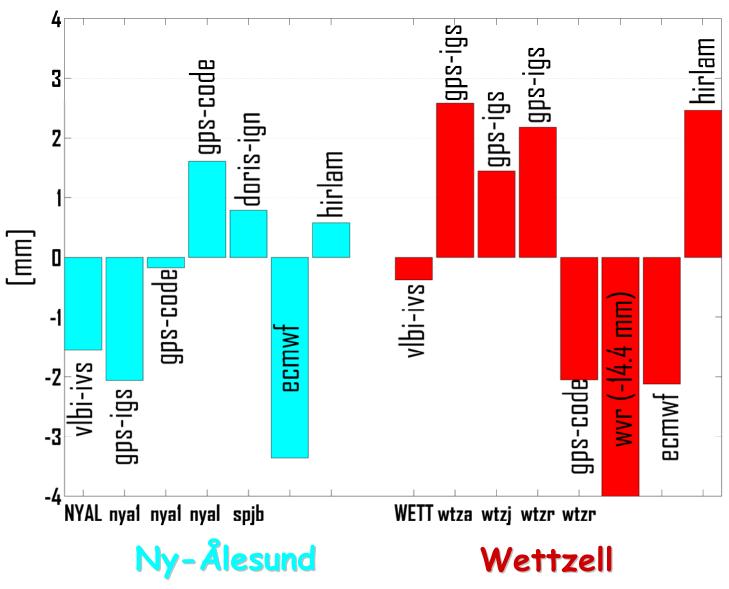






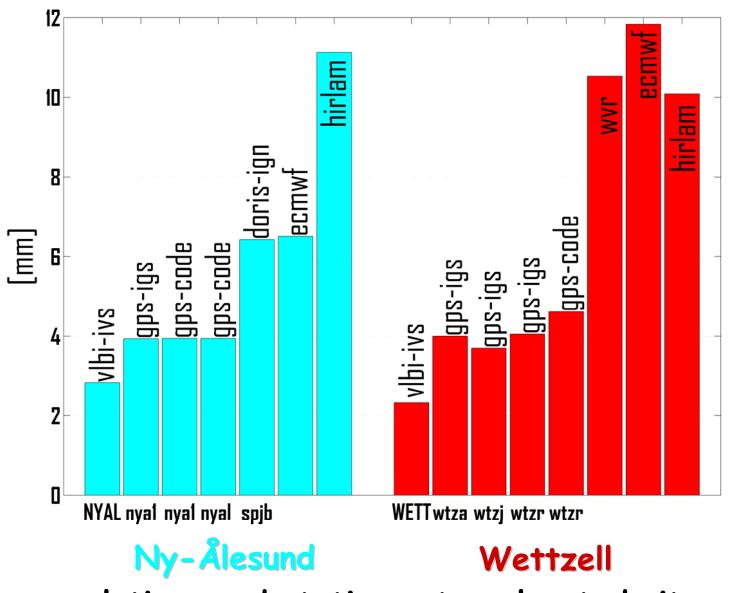


Biases of ZTDs between VieVS and other solutions

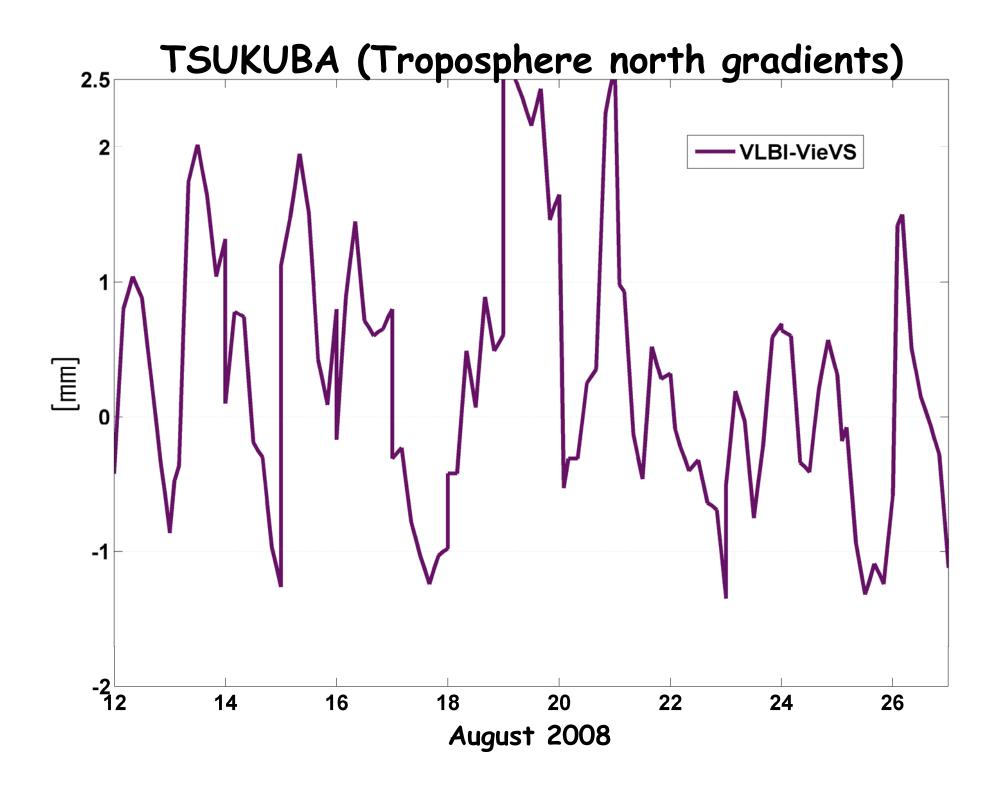


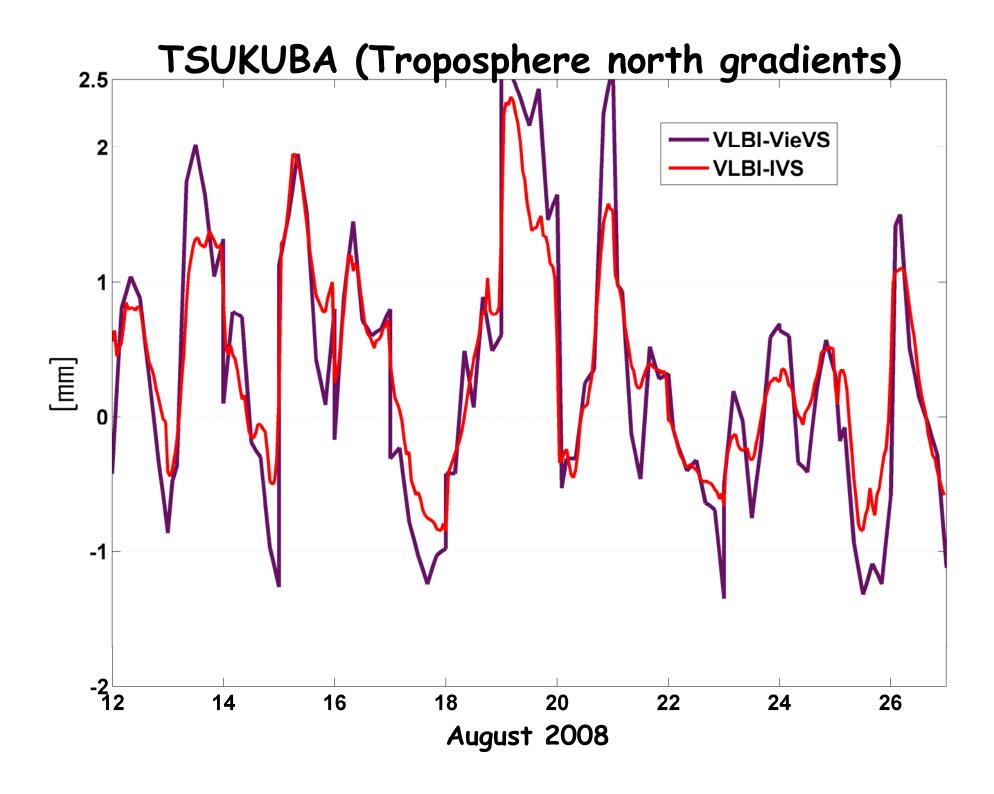
solutions and stations at co-located sites

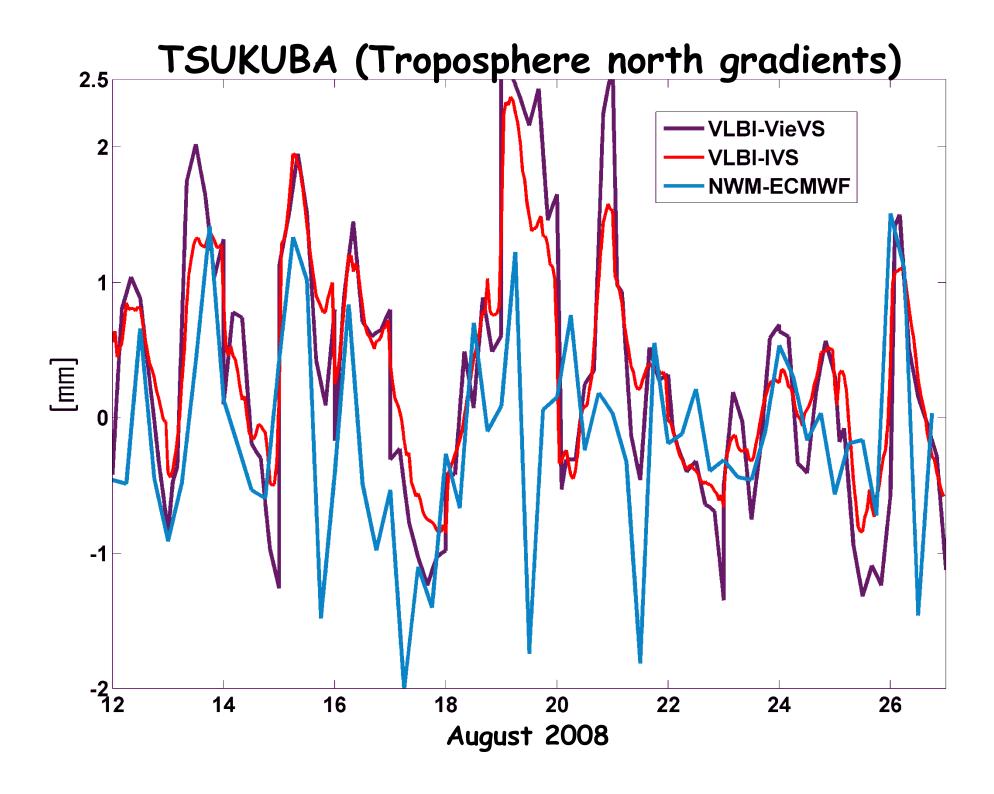
Std. dev. of ZTDs between VieVS and other solutions

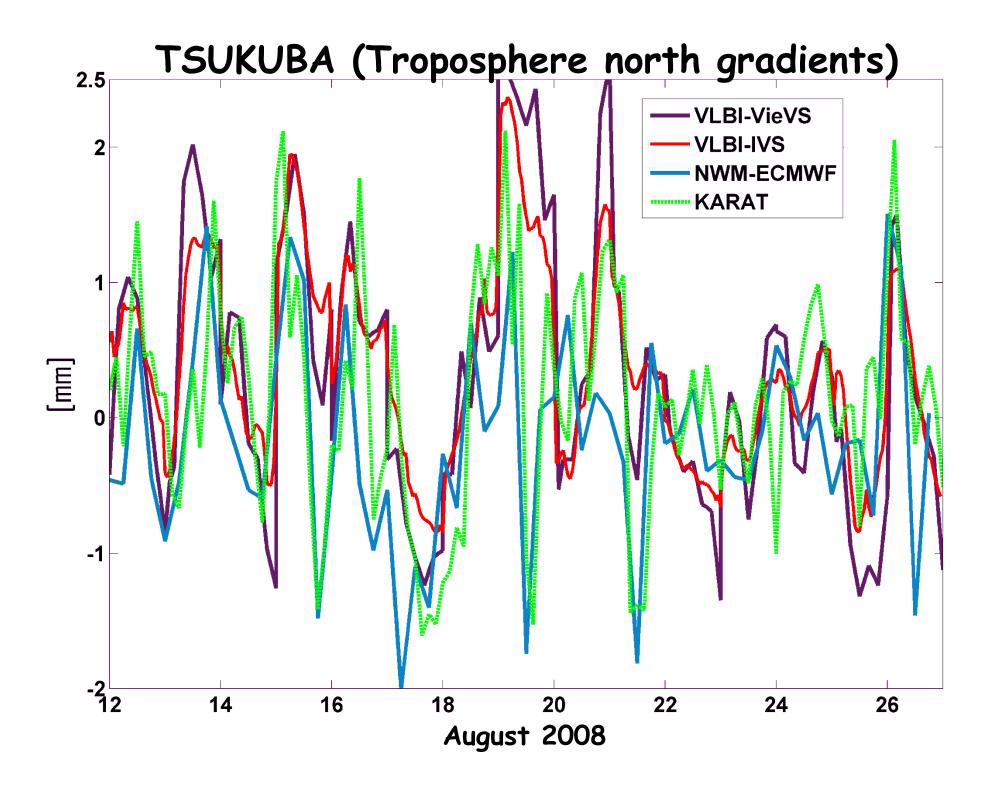


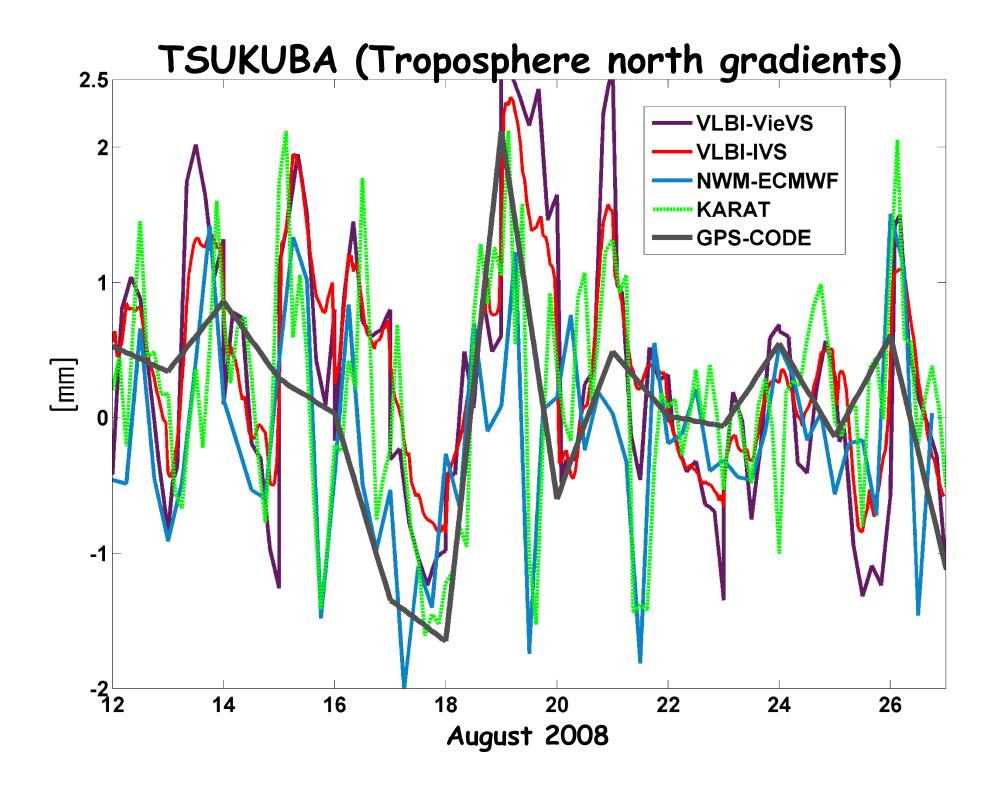
solutions and stations at co-located sites



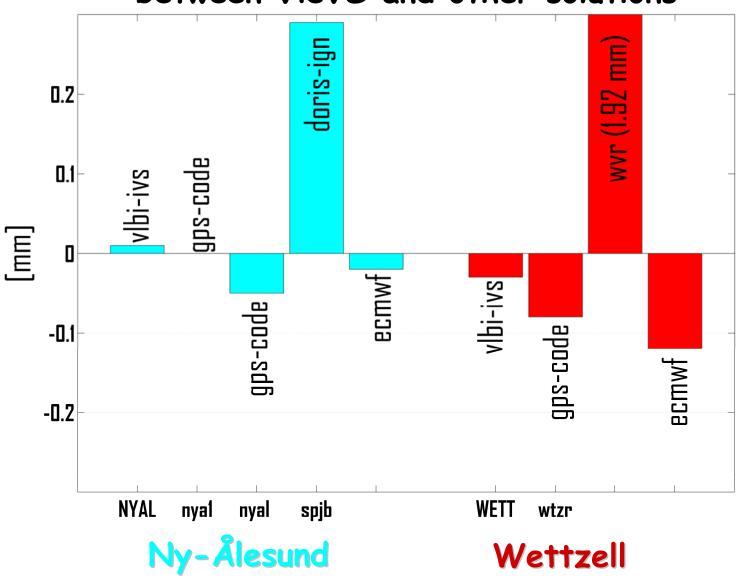






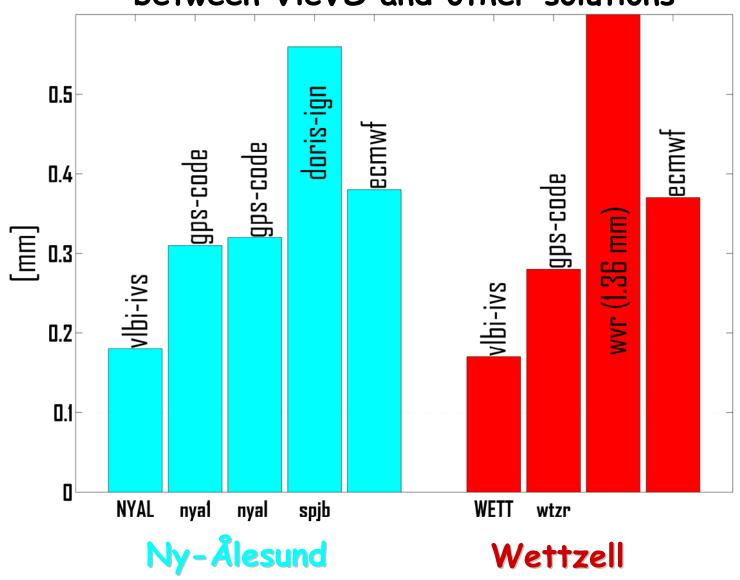


Biases of troposphere north gradients between VieVS and other solutions



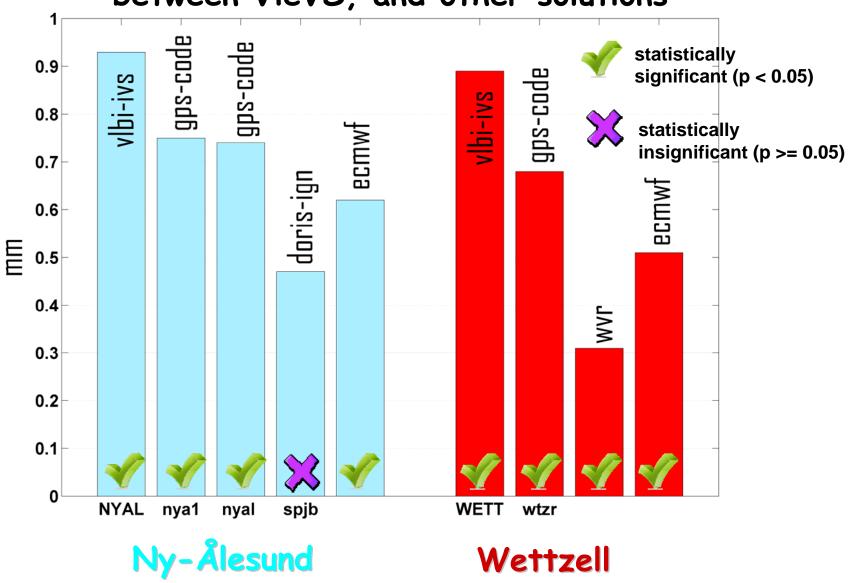
solutions and stations at co-located sites

Standard deviations of troposphere north gradients between VieVS and other solutions



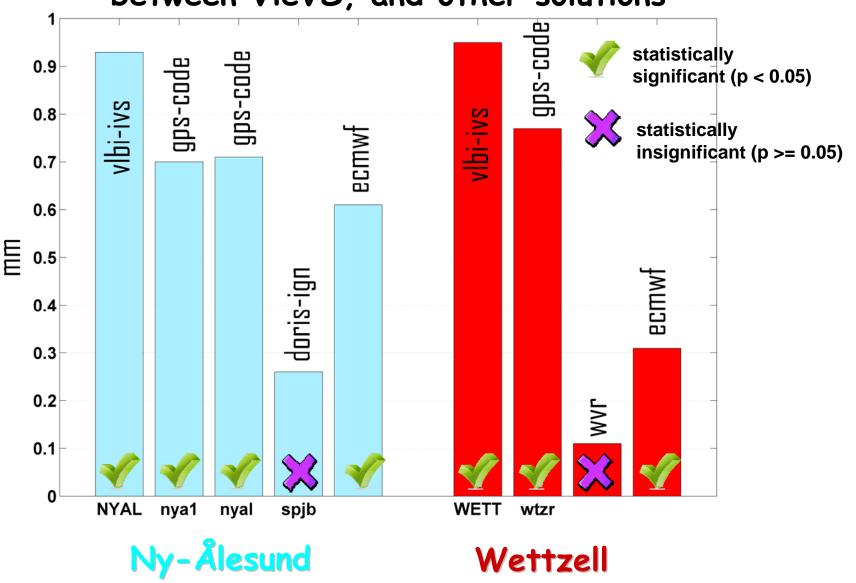
solutions and stations at co-located sites

Correlations of troposphere north gradients between VieVS, and other solutions



solutions and stations at co-located sites

Correlations of troposphere east gradients between VieVS, and other solutions



solutions and stations at co-located sites

Conclusions

- ZTD estimates of space geodetic techniques (VLBI, GPS, DORIS) for different solutions (VieVS, IVS, IGN, IGS, CODE) generally agree at the 0.5-1 cm level.
- ZTD estimates of space geodetic techniques and other techniques/models (WVR, ECMWF, HIRLAM, JMA-KARAT) agree with each other better than 2 cm. Correlation coefficients are typically > 0.9 (not shown in the presentation).
- For both ZTDs and gradients the best agreement is found when doing an intra-technique comparison (e.g. VieVS and IVS, CODE and IGS).
- •The best inter-technique agreement both for ZTD and gradient estimates is achieved between VLBI and GPS.
- Correlations of gradients between techniques are mostly below 0.6.

Acknowledgements

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Thank You.